Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

Tehran Urban & Suburban Railway Operation Company

Metro Cars Propulsion Design & Production Project

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JAHAD DANESHGAHI ELM VA SANNAT JULY 2022								
0	July 2022	First Issue	M.R.Shakour	M.Afjeh	M.Fazeli	M.Fazeli		
REV.	DATE	DESCRIPTION	Prepare	Check	Confirm	Approve		

Address: No.188 – MALEKLOO St. – South of Iran University of Science and Technology – North HEYDARKHANI St. – FARJAM St. – NARMAK – TEHRAN.



Phone: +982177455001-2 Email: info@jdevs.ir



JDEVS

Traction analysis for 4 lines



SHEET	RI	EV	IS	IO]	N	REMARK	SHEET	R	EV	ISI	[0]	N	REMARK	SHEET	R	E	VIS	SIC)N	REMARK
	0	1	2	3	4			0	1	2	3	4			0	1	2	3	4	
1	Х						31	Х						61						
2	Х						32	Х						62						
3	Х						33	Х						63						
4	Х						34							64						
5	Х						35							65						
6	Х						36							66						
7	Х						37							67						
8	Х						38							68						
9	Х						39							69						
10	Х						40							70						
11	Х						41							71						
12	Х						42							72						
13	Х						43							73						
14	Х						44							74						
15	Х						45							75						
16	Х						46							76						
17	Х						47							77						
18	Х						48							78						
19	Х						49							79						
20	Х						50							80						
21	Х						51							81						
22	Х						52							82						
23	Х						53							83						
24	Х						54							84						
25	Х						55							85						
26	Х						56							86						
27	Х						57							87						
28	Х						58							88						
29	Χ						59							89						
30	Х						60							90		[[



Page 2 of 33

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

In The Name of Allah

Vehicle Data

Train Configuration The train configuration is according to Mc-T-M-M-T-Mc.

Mc Motor car with driver's cab

T Trailer car

M Motor car

n_car 7

Num_motor 20

Weight

according to the proposal of the Metran working group is as follows:

Dynamic Weight 22 Ton Rotational mass

AW0 = 256.584 Ton AW1 = 278.004 Ton AW2 = 320.494 Ton

AW3 = 348.284 Ton

Total Train Resistance

The Davis formula is used for running resistance

 $Frr = A + B \cdot v + C \cdot v [N]$

	AW0	AW1	AW2	AW3
А	5282	5419	5691	5868
В	35.91	38.91	44.86	48.75
С	0.81	0.81	0.81	0.81



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

Wheel Diameter

New: 860 mm

Half worn: 825 mm (base of Performance Calculations)

Fully worn: 790 mm

Gear parameter

efficiency gear: 0.98

gear ratio: 7.06

Motor

F base:56	[Hz]
motor nominal	torque: 1036 [N.m]
nominal line v	oltage: 585 V .: 825 Vdc , Propulsion: 750Vdc
nominal power	180 Kw braking

Line parameter

Max Acceleration :1 m/s2 on Propulsion and 1.1 m/s2 on braking

Max gradient: 5%

Adhesion Coefficient

The adhesion coefficient according to the proposal of the Metran working group is as follows:

$$\mu_{AD} = \frac{25}{100 + V} \qquad \text{V: Km/h}$$



Metro Cars Propulsion Design & Production Project	IDEVS	
Traction analysis for 4 lines	JDEV3	
JDEVS-MPDP-PS-PY-165-00		Page 5 of 33



1.Tractive force at different car weights e.g. a $_{max}=1 \text{ m/s}^2$

2.Braking force at different car weights e.g.



a max=1.1 m/s² at aw $_0/aw_1$

From 10 to 5 km / h reduced in the form of ramps, the amount of electric braking force is reduced and from 5 to 0 km / h only air braking is applied. (See Fig. 27)

Metro Cars Propulsion Design & Production Project Traction analysis for 4 lines	JDEVS	(142) (142)
JDEVS-MPDP-PS-PY-165-00		Page 6 of 33

3. Standard duty cycle at AW3 & Gradient 0% - velocity and acceleration as a function of time e.g.



4. Standard duty cycle at AW3 & Gradient 0% - velocity and acceleration as a function of distance e.g.



Metro Cars Propulsion Design & Production Project	IDEVS	(جهاد)
Traction analysis for 4 lines	JPEV3	
JDEVS-MPDP-PS-PY-165-00		Page 7 of 33

5. Standard duty cycle at AW3 & Gradient 0% – Traction force and power of one MCM as a function of time e.g.



6- Standard duty cycle at AW3 & Gradient 0% –Current as a function of time e.g.



Metro Cars Propulsion Design & Production Project	IDEVE	
Traction analysis for 4 lines		
JDEVS-MPDP-PS-PY-165-00		Page 8 of 33

7- Standard duty cycle at AW3 & Gradient 0% –velocity and acceleration as a function of distance e.g.



8- Standard duty cycle at AW3 & Gradient 0% –velocity and acceleration as a function of time e.g.



Metro Cars Propulsion Design & Production Project	IDEVS	(جهاد)
Traction analysis for 4 lines	J9EV3	
JDEVS-MPDP-PS-PY-165-00		Page 9 of 33

9- Standard duty cycle at AW3 & Gradient 0% –velocity and reduce acceleration as a function of time e.g.



10- Standard duty cycle at AW3 & Gradient 0% –velocity and reduce acceleration as a function of distance e.g.



Metro Cars Propulsion Design & Production Project	IDEVS	(جهاد)
Traction analysis for 4 lines	J9EV3	
JDEVS-MPDP-PS-PY-165-00		Page 10 of 33

11- Standard duty cycle at AW3 & Gradient 5% –velocity and acceleration as a function of time e.g.



12- Standard duty cycle at AW3 & Gradient 5% –velocity and acceleration as a function of distance e.g.



Metro Cars Propulsion Design & Production Project	IDEVS	(جهاد)
Traction analysis for 4 lines	JEVS	
JDEVS-MPDP-PS-PY-165-00		Page 11 of 33

13.Degraded mode (90%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of time e.g.



14.Degraded mode (90%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of distance e.g.



Metro Cars Propulsion Design & Production Project	IDEVS	جهاد ا
Traction analysis for 4 lines	UDE VO	
JDEVS-MPDP-PS-PY-165-00		Page 12 of 33

15.Degraded mode (80%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of distance e.g.



16.Degraded mode (80%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of time e.g.



Metro Cars Propulsion Design & Production Project	JDEVS	(جهاد)
Traction analysis for 4 lines		
JDEVS-MPDP-PS-PY-165-00		Page 13 of 33

17.Degraded mode (70%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of distance e.g.



18.Degraded mode (70%) Gradient 5% at Aw3 -velocity, acceleration and mean acceleration as a function of time e.g.



Metro Cars Propulsion Design & Production Project	JDEVS	(جهاد)
Traction analysis for 4 lines		
JDEVS-MPDP-PS-PY-165-00		Page 14 of 33

19. Towing mode, Gradient 5% at Aw0 for AW2 -velocity, acceleration and mean acceleration as a function of distance e.g.



20. Towing mode, Gradient 5% at Aw0 for AW2 -velocity, acceleration and mean acceleration as a function of time e.g.



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 15 of 33

21. Track simulation at aw3 uphill – line 3 Total trip 47 min Regeneration energy 490 Kwh Tractive energy 1160 Kwh Total stops at stations 8.3 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 16 of 33

22. Track simulation at aw3 downhill – line 3 Total trip 46 min Regeneration energy 1020 Kwh Tractive energy 560 Kwh Total stops at stations 8.3 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

23. Track simulation at aw3 uphill Degraded 70% – line 3 Total trip 55 min Regeneration energy 370 Kwh Tractive energy 1030 Kwh Total stops at stations 8.3 min



JDEVS

Page 17 of 33

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

24. Track simulation at aw3 downhill Degraded 70% – line 3 Total trip 53 min Regeneration energy 930 Kwh Tractive energy 460 Kwh Total stops at stations 8.3 min





Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 19 of 33

25. Track simulation at aw3 uphill – line 4 Total trip 31 min Regeneration energy 400 Kwh Tractive energy 520 Kwh Total stops at stations 6.3 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 20 of 33

26. Track simulation at aw3 downhill – line 4 Total trip 31 min Regeneration energy 430 Kwh Tractive energy 450 Kwh Total stops at stations 6.3 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

27. Track simulation at aw3 uphill Degraded 70% – line 4 Total trip 34 min Regeneration energy 350 Kwh Tractive energy 470 Kwh Total stops at stations 6.3 min



JDEVS

Page 21 of 33

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

28. Track simulation at aw3 downhill Degraded 70% – line 4 Total trip 34 min Regeneration energy 380 Kwh Tractive energy 400 Kwh Total stops at stations 6.3 min



JDEVS

Page 22 of 33

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 23 of 33

29. Track simulation at aw3 uphill – line 6 Total trip 47 min Regeneration energy 430 Kwh Tractive energy 900 Kwh Total stops at stations 8.6 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 24 of 33

30. Track simulation at aw3 downhill – line 6 Total trip 46 min Regeneration energy 770 Kwh Tractive energy 500 Kwh Total stops at stations 8.6 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 25 of 33

31. Track simulation at aw3 uphill Degraded 70% – line 6 Total trip 52 min
Regeneration energy 370 Kwh
Tractive energy 840 Kwh
Total stops at stations 8.6 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

32. Track simulation at aw3 downhill Degraded 70% – line 6 Total trip 51 min Regeneration energy 720 Kwh Tractive energy 440 Kwh Total stops at stations 8.6 min



JDEVS

Page 26 of 33

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 27 of 33

33. Track simulation at aw3 uphill – line 7

Total trip 37 min

Regeneration energy 370 Kwh

Tractive energy 900 Kwh



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 28 of 33

34. Track simulation at aw3 downhill – line 7

Total trip 36 min

Regeneration energy 800 Kwh

Tractive energy 430 Kwh



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 29 of 33

35. Track simulation at aw3 uphill Degraded 70% line 7

Regeneration energy 277 Kwh

Tractive energy 797 Kwh

Total trip 44 min



Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

JDEVS Page 30 of 33

36. Track simulation at aw3 downhill Degraded 70% line 7

Regeneration energy 721 Kwh

Tractive energy 344 Kwh

Total trip 42 min



Metro Cars Propulsion Design & Production Project	JDEVS	
Traction analysis for 4 lines		
JDEVS-MPDP-PS-PY-165-00		Page 31 of 33

37-Tractive Effort as a Function of Line Voltage (Used Wheels as Worst Case)



Line Voltage [V]

Traction analysis for 4 lines

JDEVS-MPDP-PS-PY-165-00

38-Tractive Effort as a Function of Speed (Used Wheels as Worst Case)



JDEVS

Page 32 of 33

Metro Cars Propulsion Design & Production Project Traction analysis for 4 lines	JDEVS	
JDEVS-MPDP-PS-PY-165-00		Page 33 of 33

39. From 10 to 5 km / h reduced in the form of ramps, the amount of electric braking force is reduced and from 5 to 0 km / h only air braking is applied.

